

Computer Science Department

TECHNICAL REPORT

VERIFICATION OF SEVERAL PARALLEL
COORDINATION PROGRAMS BASED ON
DESCRIPTIONS OF THEIR REACHABILITY SETS

by

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Abstract - A method for verifying parallel programs is applied to several examples (PV-semaphore, "busy-wait" synchronization, "cessation of activity" synchronization, "readers-writers"). The graph of all program states and state transitions is represented in a special compact form independent of the number N of processing elements. This representation aids in verifying certain correctness properties that can not be easily expressed in the form "predicate(state)". In each of the above mentioned examples a special "reachability tree" is developed whose nodes are some subsets of the set of all reachable states. The root is the initial state and moving down the tree corresponds to some processors advancing their execution. In the presented examples the size of this tree is independent of N . The notion of compact program is introduced: roughly speaking a parallel program is compact if there exists a boundary, independent of N , on time required to reach any state. Examples of non-compact programs are represented.

Index Terms - correctness proof, program verification, concurrent processes, synchronization, semaphore, liveness property, mutual exclusion, deadlock.

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1. Introduction.

This paper considers verification problems typified by following (incorrect) implementation of Dijkstra's PV-semaphore.

COMMENT P-section

```
P1:  p <- REPADD(sem,-1)
      if (p > 0) then go to P3
```

```
P2:  REPADD (sem,1)
      go to P1
```

COMMENT critical section, protected by sem

```
P3:  {...}
```

COMMENT V-section

```
      REPADD (sem,1)
      go to P1
```

This code is supposed to be executed by all the processing elements (PEs) of a parallel computer. In this code, sem is a public variable accessible by each PE; initially sem = 1; p is a private variable, i.e. each PE maintains its own copy of p; all PEs begin at P1; expression REPADD(sem,constant) is used for the function-with-side-effect that replaces sem by (sem + constant) and returns the new value of sem. The REPADD operation is indivisible in the sense that the result of concurrently executed REPADD operations is the same as if the operations were executed in some unspecified serial order (see [5]).

It was shown in [4] (see also [5]) that after the first execution of the critical section P3, the following unacceptable race condition can occur: All the PEs are infinitely executing the loop between the statements P1 and P2, and sem < 0, which prevents any PE from entering the critical section. Note that such "parallel bugs" are particularly hard to discover so a mechanical method for exposing them would be very helpful. Consider the following table that lists all states reachable when a 2-processor parallel computer executes the above program. In this table we characterize states by giving the values of sem and the number of PEs beginning execution of each statement P1, P2, P3. (We do

not consider states in which a PE has executed part, but not all, of a statement). For each state we also indicate the states resulting from a PE completing execution of its current statement and moving to another.

s_1	(initial state) [P1: 2 PEs, P2: no PEs, P3: no PEs; sem = 1] move of 1 PE from P1 to P3 leads to s_2
s_2	[P1: 1 PE, P2: no PEs, P3: 1 PE; sem = 0] move of 1 PE from P1 to P2 leads to s_3 move of 1 PE from P3 to P1 leads to s_1
s_3	[P1: no PEs, P2: 1 PE, P3: 1 PE; sem = -1] move of 1 PE from P2 to P1 leads to s_2 move of 1 PE from P3 to P1 leads to s_4
s_4	[P1: 1 PE, P2: 1 PE, P3: no PEs; sem = 0] move of 1 PE from P1 to P2 leads to s_5 move of 1 PE from P2 to P1 leads to s_1
s_5	[P1: no PEs, P2: 2 PEs, P3: no PEs; sem = -1] move of 1 PE from P2 to P1 leads to s_4

Table 1.1

This type of table can be produced mechanically. In fact, a formal procedure exists and has been programmed by the author that can analyse programs like the one given above for any fixed number of PEs. We do not present a detailed description of this procedure in the present paper and only briefly outline it here. This procedure, first, creates the table of all reachable states (like table 1.1 above). Then the procedure analyses the directed graph representing all reachable states of the program and all possible transitions. For our example the nodes of the graph are s_1, s_2, s_3, s_4, s_5 , and the arcs are $(s_1, s_2), (s_2, s_3), (s_2, s_1), (s_3, s_2), (s_3, s_4), (s_4, s_5), (s_4, s_1), (s_5, s_1)$. Each of the arcs corresponds to one move listed in the above table. The race condition mentioned above appears as a strongly connected component $s_4 \rightarrow s_5 \rightarrow s_4$ of the subgraph generated by the predicate "there are no PEs at P3" in this graph. We will see that the well-known "finite delay property" (discussed below) also must be satisfied by the strongly connected component in order to generate a race condition.

We now show that the verificational approach started by Floyd for sequential programs and extended ([2], [7]) to concurrent programs would not expose the described above race condition. We can rewrite our REPADDs as "WITH-WHEN": cf [7]:

```
p <- REPADD (sem, const)
```

is the same as

```
WITH sem WHEN true DO {sem <- sem + const; p <- sem}
```

Here `p` is a private variable, `sem` is a public variable and `const` is a constant, the notation "WITH `sem`" represents the indivisibility of resource `sem`. The incorrect semaphore implementation given above is "deadlock-free" according to [7] because all processes inside WITH-WHEN sections can not be "blocked". (Blocking occurs if there exists a reachable state with all WHEN conditions false. But in our example all these conditions are identically true).

The semaphore program is "improved" in [5]. But is the new program (given in section 3) correct? We have applied our verification procedure for parallel computers with various numbers of PEs and no bug was found.¹ (The time and memory requirements increase rapidly with the number of PEs.)

Can one develop for an arbitrary number of PEs a compact representation of table 1.1 containing all information about the program behavior? An example of such a representation has been given by Dijkstra [4]. While analysing a "producer-consumer" program Dijkstra introduces a set `S` of states of the program and analyses all possible state transitions. He shows that all transitions from a state in `S` yield a state in `S`. This analysis then is applied to verify a property of the form "predicate(state)".

¹In [3] a similar approach was applied to analyse a parallel program, however the reachability set was developed only for 2 PEs.

But this approach is not detailed in [4]. It was not shown that all states in S are reachable, and no procedure was given to generate S . Also the possibility of using this method to investigate race condition was not mentioned, although the race condition described above was exposed in the very same paper.²

The present paper analyses several programs in which all execution states are represented in a special compact form for an arbitrary number of PEs. This technique aids in verifying some correctness properties of such programs, especially, those properties that can not be easily expressed in the form "predicate (state)", e.g. the absence of a race condition.³

²The author finds [4] to be a very stimulating work. However based on the existence of the race condition in the semaphore program the primitive REPADD was rejected as not appropriate for solving the mutual exclusion problem. In fact, this and many other problems can be solved using REPADD (see [5]).

³A few recent works such as [8] study the liveness property of parallel programs. The absence of a race condition in the semaphore example above would be such a property. However, unlike the present work [8] assumes implicitly that the number of processes is fixed, and only presents program examples of this kind. The author believes that this assumption greatly simplifies the analysis needed and as mentioned above, permits automatic verification.

2. Some definitions.

We wish to define a parallel program schema that will be called an abstract program. An abstract program represents a class of concrete parallel programs and is defined by the following:

- a directed graph G (which represents the "body" of the concrete programs). The vertices of the graph are called positions. Let $\{P_i; i=1, \dots, k\}$ be the set of positions of G ; G has two kinds of the positions: interior and exterior described below. As usual we say that P_j follows P_i , if G has an arc (P_i, P_j) ;

- a set C of counters, such that to each interior position P there is associated a counter $c=c(P)$. Note that one counter can be associated with several positions. C corresponds to the public variables in the concrete program. Since the programs considered below have no private variables, C coincides with the set of all program variables⁴;

- a set $F = \{f_i\}$ of replacing functions, $f_i: \text{Range}(c(P_i)) \rightarrow \text{Range}(c(P_i))$. Each interior position has a unique replacing function;

- a set $D = \{d_i\}$ of directing functions; d_i assigns to each value of $c(P_i)$ a position that follows P_i . Each interior position has its own directing function. If no position follows P_i then $d_i(c(P_i))$ is the empty set.

The distinction between interior and exterior positions is that the former usually represent the control flow of a concrete program represented by the abstract program; whereas the latter represent the

⁴If there are private variables in the program, which can not be considered as counters, one can apply a "replicating code" technique to get rid of them. We give an example of how this technique works in section 4. A more detailed explanation of this technique as well as some other general issues concerning the verification problem are to follow in a future paper.

control flow of other "exterior" concrete programs. In the examples below this point will become clearer.

In the following "program" will mean an abstract program unless otherwise specified.

The execution state or simply the state of a program is the vector

$$\text{state} = (n_1, \dots, n_k; c_1, \dots, c_r),$$

where n_i is the current number of processing elements (PEs) at position P_i , $i=1, \dots, k$; $N = n_1 + \dots + n_k$ is the total number of PEs; c_i is as above; and r is the number of distinct counters.

We assign meaning to the given program (G, C, F, D) with a given initial state s_0 (and thus a given N) by defining a set of possible execution histories (or simply histories). Such a history is a sequence of states s_0, s_1, \dots as specified by the following (nondeterministic) procedure.

```

step <- 0; CurrentState <- s0
REPEAT
  if possible, choose a position Pi such that
    ni is positive and some position follows Pi;
  IF such a Pi does not exist
  THEN Finished <- TRUE
  ELSE
    BEGIN
      IF Pi is interior
      THEN
        BEGIN
          replace the value of the associated
            counter    c(Pi) <- fi(c(Pi));
          define the new position Pj <- di(c(Pi))
        END
      ELSE (Pi is exterior) choose a position Pj
        following Pi;
      move one PE from Pi to Pj, namely
        ni <- ni - 1,    nj <- nj + 1
        COMMENT if i=j, then ni does not change.
    END
  step <- step + 1; sstep <- CurrentState
UNTIL Finished = TRUE

```

Note that histories may be of infinite length. In the examples considered below each position has at least one successor; in such cases all histories are of infinite length.

Starting with a given initial state s_0 one can generate the set $R = R(s_0)$ of all reachable states by developing all possible histories. The reachability directed graph $\Delta = \Delta(s_0)$ is defined as follows: the node set of Δ is R and the arcs are the possible transitions, i.e. all pairs (s_i, s_{i+1}) determined by the procedure given above.

Now we wish to present our abstract program in a form closer to the usual representation of a concrete program. We will use the expression $\text{Replace-}f(c)$ for the function-with-side-effect that replaces c by $f(c)$ and returns the new value of c . In this new representation, the program will be written as an unordered set of statements each of which corresponds to a position of G . There are two kinds of statements: For each interior position P_i the corresponding statement is

(I) P_i : go to $d_i(\text{Replace-}f_i(c(P_i)))$

For each exterior position P_i the corresponding statement is

(E) P_i : go to P_{j_1} or P_{j_2} or...or P_{j_m}

where P_{j_1}, \dots, P_{j_m} follow P_i . The expression "go to empty", that occurs when no position follows P_i , should be understood as the empty statement "do nothing".

In the example programs to follow the statement order will be significant because we adopt the usual convention that if no "go to" appears in the statement corresponding to P_i , a "go to the statement corresponding to $P(i+1)$ " is assumed. The following statement forms (all are special cases of (I) and (E)) will be used in the examples. (The expression $\text{REPADD}(\text{counter}, \text{constant})$ means $\text{Replace-}f(\text{counter})$ with $f(x) = x + \text{constant}$.)

- (I1) Pi: counter \leftarrow constant
- (I2) Pi: counter \leftarrow constant
go to Pj
- (I3) Pi: if predicate(counter) then go to Pj
- (I4) Pi: if predicate(counter) then go to Pj₁
go to Pj₂
- (I5) Pi: REPADD(counter, constant)
- (I6) Pi: REPADD(counter, constant)
go to Pj
- (I7) Pi: if (predicate(REPADD(counter, constant))) then go to Pj
- (I8) Pi: if (predicate(REPADD(counter, constant))) then go to Pj₁
go to Pj₂
- (E1) Pi: go to Pj
- (E2) Pi: go to Pj₁ or Pj₂

In subsequent examples when referring to a program we will mean a family of programs parameterized by N. Replacing functions, directing functions and the initial state (but not the graph G) may depend on N. In statements (I) and (E) we allow predicates and constants to depend on N.

3. Semaphore.

The semaphore program of [5] can be represented by the following code, where we use star (*) to represent the current position, and {...} to represent a basic block (i.e. single entry single exit) that does not access the counters. The initial state s_0 in this and subsequent examples is $(N, 0, \dots, 0; c_1, \dots, c_r)$, i.e. all N PEs begin at P1. In this example there is only one counter, sem, which has the initial value 1.

P1: {...}

COMMENT P-section

P2: if (sem < 0) then go to *

P3: if (REPADD (sem,-1) > 0) then go to P5

P4: REPADD (sem,1)
go to P2

COMMENT critical section, protected by sem

P5: {...}

COMMENT V-section

P6: REPADD (sem,1)
go to P1

As in [5] the following two assertions are to be verified about this program:

(A1) No more than 1 PE can be in the critical section at any one time.

(A2) For any time t such that no PEs are in the critical section at time t , there exists a time $t' > t$ such that some PE is in the critical section at time t' .

While analysing this (relatively simple) program we will introduce several techniques and notions used in subsequent examples.

First, we are to represent the concrete program as an abstract program of section 2. The critical section "P5: {...}" and the other section denoted {...} do not effect the analysis. Thus we can consider the following abbreviated abstract program.

```

P1:  if (sem ≤ 0) then go to *
P2:  if (REPADD (sem,-1) > 0) then go to P4
P3:  REPADD (sem,1)
      go to P1
P4:  REPADD (sem,1)
      go to P1

```

Note that statements P1, P2, P3, P4 in this code are of the form (I3), (I7), (I6), and (I6), respectively.

We next show that $R(s_0) \supset S1 \cup \dots \cup S5$, where S_i , $i=1,\dots,5$ are the following sets (all n_i are supposed to be nonnegative integers):

$$\begin{aligned}
 S1 &= \{s_0\} = \{s ; n_1 = N, \text{sem} = 1\} \\
 S2 &= \{s ; n_1 + n_2 = N, \text{sem} = 1\} \\
 S3 &= \{s ; n_1 + n_2 = N-1, n_4 = 1, \text{sem} = 0\} \\
 S4 &= \{s ; n_1 + n_2 + n_3 = N-1, n_4 = 1, \text{sem} = -n_3\} \\
 S5 &= \{s ; n_1 + n_2 + n_3 = N, n_1 > 1, n_3 > 1, \text{sem} = 1 - n_3\}
 \end{aligned}$$

Clearly, $R \supset S1$.

Consider the only state $s_0 = \{N,0,0,0;1\}$ in $S1$, i.e. the state in which all PEs are at P1 and the public variable $\text{sem} = 1$. Looking at the code we see that in state s_0 from 1 to N PEs can move from P1 to P2; such moves generate the set

$$S2' = \{s ; n_1 + n_2 = N, n_2 > 1, \text{sem} = 1\}$$

Note that $S2 = S2' \cup S1$ and therefore all states in $S2$ are reachable, i.e. $R \supset S2$.

Consider those states s in $S2$ from which PEs can move along the arc $P2 \rightarrow P4$, i.e. those states satisfying the condition $n_2 > 1$. Note that in these states at least one PE is at P2 and $\text{sem} = 1$. Looking at

the code we see that at most 1 PE can move from P2 to P4; such moves generate S3 and therefore all states in S3 are reachable, i.e. $R \supset S3$.

Consider those states s in S3 from which PEs can move along the arc P2 \rightarrow P3, i.e. those states satisfying the condition $n_2 > 1$. Note that in these states at least one PE is at P2 and $sem \leq 0$. Looking at the code we see that from 1 to n_2 PEs can move from P2 to P3; such moves generate the set

$$S4' = \{s ; n_1 + n_2 + n_3 = N-1, n_4 = 1, n_3 > 1, sem = -n_3\}$$

Note that $S4 = S4' \cup S3$ and therefore all states in S4 are reachable, i.e. $R \supset S4$.

Consider those states s in S4 that have at least 1 PE at P3, i.e. those states satisfying the condition $n_3 > 1$. Looking at the code we see that 1 PE can move from P4 to P1; such moves generate the set S5 and therefore all states from S5 are reachable, i.e. $R \supset S5$.

This implies that each S_i contains only reachable states, i.e.

$$(1) \quad R \supset \bigcup_{i=1}^5 S_i$$

The above arguments may be abbreviated as in table 3.1.

REACHABILITY TREE

- S1 $n_1 = N, \text{sem} = 1$
moves from P1 to P2 lead to S2
- S2 $n_1 + n_2 = N, \text{sem} = 1$
moves from P2 to P4 lead to S3
- S3 $n_1 + n_2 = N-1, n_4 = 1, \text{sem} = 0$
moves from P2 to P3 lead to S4
- S4 $n_1 + n_2 + n_3 = N-1, n_4 = 1, \text{sem} = -n_3$
moves from P4 to P1 lead to S5, if $n_3 > 1$
- S5 $n_1 + n_2 + n_3 = N, n_1 > 1, n_3 > 1, \text{sem} = 1-n_3$

Table 3.1

We will use the REACHABILITY TREE in future examples without explicitly noting that all states represented in the table are reachable.

The word "tree" in the name of the table is due to the fact that the table can be viewed as a directed graph, which is in fact a directed tree. The nodes of this graph are the S_i in the table and the arcs are pairs (S_i, S_j) such that some move starting at S_i "leads to S_j " according to the table. For the semaphore example the nodes are $\{S1, S2, S3, S4, S5\}$ and the arcs are $\{(S1, S2), (S2, S3), (S3, S4), (S4, S5)\}$, so that the tree is simply a sequence $S1 \rightarrow S2 \rightarrow S3 \rightarrow S4 \rightarrow S5$. For subsequent examples the REACHABILITY TREE can be more complex.

Recall the restriction $n_3 > 1$ in moves from S4 to S5. Let us call this kind of restriction a branching condition. In the above example n_3 , the only variable appearing in a branching condition, does not change in value during the move controlled by the branching condition; but sometimes a branching condition involves several variables some of which change in value during the move. In such a case the predicate must be true for the states obtained after the move.

When the number of nodes in the REACHABILITY TREE is small (as is the case for the simple semaphore program), the REACHABILITY TREE can be used directly as an instrument to observe the behavior of the program. In other examples the REACHABILITY TREE is large and

reductions are helpful. Let us demonstrate one such a reduction for our simple example.

Consider the set of sets $\Psi = \{S_2, S_4, S_5\}$. Ψ has the property that it is a minimal subset of the set $\Phi = \{S_1, S_2, S_3, S_4, S_5\}$ such that for any element S_i of Φ there exists an element S_j from Ψ such that $S_i \subset S_j$. In fact we have the following inclusions:

INCLUSIONS

$$S_1 \subset S_2; S_3 \subset S_4$$

Moreover none of the elements from Ψ is a subset of any of the other 2 elements of Ψ . Thus we can omit S_1 and S_3 without losing any states.

In the REACHABILITY TREE above, for each set S_i that is an element of Φ we only listed some of the possible moves. The following REACHABILITY SET DESCRIPTION (RSD) is the final product of the technique. It lists, for each S_i in Ψ , all possible moves.

REACHABILITY SET DESCRIPTION

- S2 $n_1 + n_2 = N$, sem = 1
 moves from P1 to P2 lead to *
 moves from P2 to P4 lead to S4
- S4 $n_1 + n_2 + n_3 = N-1$, $n_4 = 1$, sem = $-n_3$
 moves from P1 to P1 lead to *
 moves from P2 to P3 lead to *
 moves from P3 to P1 lead to *
 moves from P4 to P1 lead to S5, if $n_3 > 1$
 or lead to S2, if $n_3 = 0$
- S5 $n_1 + n_2 + n_3 = N$, $n_1 > 1$, $n_3 > 1$, sem = $1-n_3$
 moves from P1 to P1 lead to *
 moves from P2 to P3 lead to *
 moves from P3 to P1 lead to *, if $n_3 > 1$
 or lead to S2, if $n_3 = 0$

Table 3.2

The phrases listed under the formulas for each S_i are called directing phrases. Each directing phrase represents a class of moves "from P_i to P_j ". We say that these moves are carried by the arc $P_i \rightarrow P_j$ (of the graph G) or that this arc carries these moves.

The RSD is closed in the sense that all moves are to sets given in the description; moreover, all possible moves are represented and the initial state belongs to S_2 . Thus we have

$$(2) \quad R \subset S_2 \cup S_4 \cup S_5.$$

Properties (1) and (2) together give

$$R = S_2 \cup S_4 \cup S_5$$

In subsequent examples a similar argument shows that R is the union of the sets presented in the RSD.

The above analysis has actually involved a hidden assumption that N is sufficiently large. For example when we considered those states s in S_3 such that $n_2 > 0$, we tacitly assumed that $N > 1$ (or else no such s exists). For each example in this paper it is easy to see that there exists an N_0 such that for all $N > N_0$ all the required states do exist. In particular, for the semaphore example just discussed, one may choose $N_0 = 2$. However, the REACHABILITY TREE and the RSD tables are actually valid for all $N > 1$ if interpreted correctly. Although for small N some sets S_i are empty and some branching conditions are unsatisfiable, no contradiction arises. This may be easily checked on a case-by-case basis.

Before analysing the semaphore program using the above RSD let us make the following general remarks.

Note that the RSD can be viewed as a directed graph Γ that differs from both the graph Δ and the REACHABILITY TREE. Namely nodes of Γ are those sets S_i appearing in the RSD and arcs of Γ correspond to the

directing phrases associated with each S_i . In the semaphore example Γ has 3 nodes corresponding to the 3 sets S_2, S_4, S_5 and has 11 arcs, corresponding to the 11 directed phrases in the RSD. For example, the Γ contains arcs (S_2, S_2) , (S_5, S_5) , and (S_5, S_2) since the phrases

moves from P_1 to P_2 lead to *

moves from P_3 to P_1 lead to *, if $n_3 > 1$
or lead to S_2 , if $n_3 = 0$

are written under the formulas for S_2 and S_5 .

For the reader's convenience we summarize the graphs defined thus far in table 3.3.

Graph	Node set	Elements of node set
G	$\{P_1, \dots, P_k\}$	program positions
Δ	R	reachable states
Γ	$\{S_{i_1}, \dots, S_{i_n} \text{ of RSD}\}$	subsets of R

Table 3.3

Let $p(s)$ be some predicate over the set R of nodes of Δ , i.e. a predicate over states of the program and S be a subset of R . By $S \bullet p$ we denote the intersection of S with $\{s; p(s)=\text{true}\}$. By $\Delta \bullet p$ we denote the subgraph of Δ induced by the predicate p , i.e. the subgraph whose node set is $R \bullet p$ and whose arcs are those of Δ connecting these nodes. The following is a general problem when analysing our programs. Given a

⁵A strongly connected component c in a directed graph g is a maximal subgraph of g such that for any two (not necessarily different) nodes of c there exists a directed path in g from the first node to the second.

predicate p find all strongly connected components⁵ (SCCs) in $\Delta \bullet p$. To find these SCCs one executes the following procedure called FIND SCC.

Step 1. Let $\{S_1, \dots, S_n\}$ be the sets constituting the RSD (these sets are also nodes of Γ). Eliminate from Γ those S_i for which corresponding sets $S_i \bullet p$ are empty and eliminate all arcs adjacent to these nodes. Note that a directing phrase can be viewed as a set of pairs of states and eliminate each arc whose corresponding directing phrase does not contain a pair both of whose components satisfy p . (Note that the first elimination is a special case of the second). The graph obtained is called $\Gamma \bullet p$.

Step 2. Find all SCCs in $\Gamma \bullet p$. For each SCC L generate its description, i.e. list every $S_i \bullet p$ with its formula and for each $S_i \bullet p$ list all directing phrases (i.e. arcs in Γ) not eliminated. Let G_L be a subgraph of G , consisting of those arcs of G that carry the moves represented in the directed phrases of L (and the vertices adjacent to these arcs).

Step 3. Find all SCCs of each graph G_L constructed in step 2.

At the end of this section we will prove that if there exists a non-empty SCC K in $\Delta \bullet p$, then at least one SCC L in $\Gamma \bullet p$ will be non-empty and the corresponding G_L will contain at least one SCC M , whose arcs carry all moves of K .

It is important to note that once the RSD is given procedure FIND SCC can be automated for a large class of predicates.

Now we interrupt our general remarks and apply the RSD to verify the semaphore program. Since (A1) is equivalent to:

$$-n_4 \leq 1 \text{ for all states,}$$

it follows immediately from the RSD.

Note that generally any assertion like $\text{predicate}(\text{state})$ can be easily verified using the RSD.

To express (A2) in terms of the description, we introduce the finite delay property (FDP).

We say that a cycle in Δ satisfies the FDP if for every position P_i such that $n_i > 0$ for some state on the cycle, there is a move from P_i that corresponds to a transition from a (possibly different) state of the cycle.

Note that the FDP fails for some cycle in Δ if and only if there is a position P_i such that n_i is a positive constant during the cycle (i.e. no PE enters or leaves P_i during the cycle execution and there is at least one PE at P_i).⁶

Now (A2) can be expressed as:

there are no cycles satisfying the FDP such that $n_4 = 0$ for all states on the cycle.

First we consider the case $N > N_0 = 2$. The problem is to observe all SCCs in Δ satisfying the condition $n_4 = 0$ for all states that form the SCC. To do so let us apply the procedure FIND SCC for $p(s) = \{n_4 = 0\}$.

⁶This definition of the FDP appears to be weaker than the one commonly used: the usual FDP means that all PEs have finite delays. Consequently it fails if one PE stays at a position P_i during the cycle execution. However, we could prove that our (weak) FDP is equivalent to the strong FDP if we refined the notion of the program state to include the identification of which PEs (rather than how many of them) are at each point in the program. Then we could establish that given a cycle of the program execution satisfying the weak FDP, one can arrange a cycle of the program execution satisfying the strong FDP and running through the same states as the first one. Note that these cycles lie not in Δ but in its refinement corresponding to the refined notion of state just given.

Step 1 gives the graph $\Gamma \bullet p$ of the form:

S2•p $n_1 + n_2 = N$, $\text{sem} = 1$
moves from P1 to P2 lead to *

S5•p $n_1 + n_2 + n_3 = N$, $n_1 > 1$, $n_3 > 1$, $\text{sem} = 1 - n_3$
moves from P1 to P1 lead to *
moves from P2 to P3 lead to *
moves from P3 to P1 lead to *, if $n_3 > 1$
or lead to S2•p, if $n_3 = 0$

Note that to obtain $\Gamma \bullet p$ from the RSD table we have crossed out node S4 and all directing phrases associated with it (because S4•p is empty) and the phrase

moves from P2 to P4 lead to S4

associated with node S2.

Now we proceed through step 2 and find out that $\Gamma \bullet p$ has the following two SCCs (which corresponds to the graphs L in the procedure FIND SCC).

First SCC in $\Gamma \bullet p$ ($L = L1$):

S2•p $n_1 + n_2 = N$, $\text{sem} = 1$
moves from P1 to P2 lead to *

Second SCC in Γ ($L = L2$):

S5•p $n_1 + n_2 + n_3 = N$, $n_1 > 1$, $n_3 > 1$, $\text{sem} = 1 - n_3$
moves from P1 to P1 lead to *
moves from P2 to P3 lead to *
moves from P3 to P1 lead to *, if $n_3 > 1$

Now we go to step 3 of the procedure and work with each SCC separately. L1 corresponds to the subgraph $G_{L1} \subset G$ which has no SCC.

L_2 gives the subgraph $G_{L_2} \subset G$ of the form $P_2 \rightarrow P_3 \rightarrow P_1 \rightarrow P_1$ which in turn has only one SCC, namely $P_1 \rightarrow P_1$.

Now we see that the loop $P_1 \rightarrow P_1$ can carry the only class of SCCs in Δ , namely

$S5 \bullet p$ $n_1 + n_2 + n_3 = N$, $n_1 \geq 1$, $n_3 \geq 1$, $\text{sem} = 1 - n_3$
 moves from P_1 to P_1 lead to $*$

But none of these SCCs satisfies the FDP, because $n_3 \geq 1$ for $S5 \bullet p$ but there is no move from P_3 . This verifies (A2) for $N \geq N_0$.

For $N < N_0$ some sets S_i become empty and/or some branching conditions become unsatisfiable. But this only makes our task easier by eliminating some cycles.

In subsequent examples we will not consider the case $N < N_0$ separately.

Now we return to the discussion of the procedure FIND SCC in the general case and prove that if there exists a SCC K in $\Delta \bullet p$, then, by applying FIND SCC, one obtains both a SCC L in $\Gamma \bullet p$ such that each node s of K lies in some node $S_i \bullet p$ of L and a SCC M in G_L that contains arcs carrying all moves represented by directing phrases of L . To prove this fact we will actually build the graphs L and M for a given SCC K .

To build L we let $s_1 \rightarrow \dots \rightarrow s_n \rightarrow s_1$ be a cycle in K including every state (such a cycle exists since K is a SCC). We associate with this cycle an infinite sequence $\Omega = \{S_{i_1} \bullet p, S_{i_2} \bullet p, \dots\}$ of nodes of $\Gamma \bullet p$ as follows. State s_1 lies in some set $S_{i_1} \bullet p$, which we define to be the first term of the sequence. To the transition $s_1 \rightarrow s_2$ there is associated an arc in $\Gamma \bullet p$ (i.e. a directing phrase written under the description of $S_{i_1} \bullet p$) which was not eliminated. This arc leads to some $S_{i_2} \bullet p$, which we define to be the second term, etc. Let $\{S_{i_1} \bullet p, \dots, S_{i_m} \bullet p\}$ be the largest initial segment of Ω composed of distinct nodes of $\Gamma \bullet p$. (Such a segment exists since $\Gamma \bullet p$ is a finite graph). Hence $S_{i_m} \bullet p = S_{i_r} \bullet p$ for some $1 < r < m$. Then except for the first

$m-1$ terms, Ω is an infinitively repeating cycle $Si_r \bullet p \rightarrow \dots \rightarrow Si_m \bullet p \rightarrow Si_r \bullet p$. It is easy to see that the subgraph L' of $\Gamma \bullet p$ induced by the set of nodes $Si_r \bullet p, Si_{r+1} \bullet p, \dots, Si_m \bullet p$ constituting the cycle is strongly-connected. We now define L to be any SCC in $\Gamma \bullet p$, containing L' . Since by construction L' has the property that each node s of K lies in some node $Si \bullet p$ of L' , so does L .

To build M we consider the same cycle $s_1 \rightarrow \dots \rightarrow s_n \rightarrow s_1$ in K . Now we associate with each move $s_i \rightarrow s_{i+1}$ of this cycle an arc in the graph G that carries this move. Arcs of G may be chosen several times and we consider them with their multiplicities. The set of arcs with the set of their endpoints forms a directed graph M'' that is connected and has the property that for each node, the number of input arcs is equal to the number of output arcs (counting the multiplicities). It follows from this that M'' is strongly-connected. Now based on M'' we form another graph M' by eliminating multiplicities from M'' . M' is a subgraph in G and is also strongly-connected since M'' is. Clearly $M' \subset G_L$. Finally, we define M to be a SCC in G_L containing M' . Since the arcs of M' carry all moves represented by directing phrases of L , so do the arcs of M .

Thus we have proved that the procedure FIND SCC is correct in the sense explained above.

4. "Busy-wait" synchronization.

In this section we will analyse a synchronisation primitive routine which was suggested by Malvin Kalos and the author of this paper and then was used in many scientific application codes developed in the "Ultracomputer Project" (see, for example, [6]). The purpose of this routine is to trap PEs until all of them complete a previous asynchronous section and then to release them for execution of another asynchronous section. Counters $sem(1)$ and $sem(2)$ are used to calculate

the number of PEs trapped by the routine. They work in a flip-flop manner so that $\text{sem}(1) / \text{sem}(2)$ is used by all odd / even invocations of the routine. The private variable index is 1 (or is 2) for odd (or even) invocations. Initially $\text{sem}(1) = \text{sem}(2) = 0$, $\text{index} = 1$. (We leave to the reader the task of showing that using only one semaphore will lead to a bug).

COMMENT asynchronous section

P1: {...}

COMMENT entry to the synchronization routine

P2: if (REPADD ($\text{sem}(\text{index}), 1$) $> N$) then go to P4

COMMENT all PES but the last one do the following

P3: if ($\text{sem}(\text{index}) > 1$) then go to *
 $\text{index} \leftarrow 3 - \text{index}$
 go to P1

COMMENT the last PE does the following

P4: $\text{sem}(\text{index}) \leftarrow 0$
 $\text{index} \leftarrow 3 - \text{index}$
 go to P1

We want to verify the following assertions about the program:

(A1) No one PE can get to the next asynchronous section P1 while some PE is still in the previous asynchronous section P1.

(A2) No one PE can be trapped in the routine P2,P3,P4 for ever.

We are not able to analyse this program as is since it has the private variable index. We can easily get rid of index by replicating the code two times. Moreover since "P1: {...}" is a basic block (i.e. single entry single exit) and does not alter $\text{sem}(\text{index})$, its presence does not effect our analysis and we can get rid of it too. Using both of this methods we obtain the following code:

P1: if (REPADD (sem(1),1) > N) then go to P3

P2: if (sem(1) > 1) then go to *
go to P4

P3: sem(1) <- 0

P4: if (REPADD (sem(2),1) > N) then go to P6

P5: if (sem(2) > 1) then go to *
go to P1

P6: sem(2) <- 0
go to P1

Note that indivisibility of the operations $\text{sem}(i) \leftarrow 0$ is provided by our interpretation of abstract programs (see section 2). However in this particular example one can use the same operations $\text{sem}(i) \leftarrow 0$ without any care about their possible divisibility in the concrete program. The indivisibility follows from the RSD below. Namely a maximum of one PE can stay in P3 and P6.

Now the properties (A1), (A2) can be expressed in the form:

(A1) No one PE can get to the section P4 while some PE is still in the section P1; no one PE can get to the section P1 while some PE is still in the section P4.

(A2) For any time t such that there are PEs in the section P1, P2, P3 (odd call) at moment t there exists a time $t' > t$ such that no PEs are in the section P1, P2, P3 at moment t' ; for any time t such that there are PEs in the section P4, P5, P6 (even call) at moment t there exists a time $t' > t$ such that no PEs are in the section P4, P5, P6 at moment t' .

REACHABILITY TREE

- S1 $n_1 = N$, $\text{sem}(1) = \text{sem}(2) = 0$
 moves from P1 to P2 lead to S2
- S2 $n_1 + n_2 = N$, $1 \leq n_2 \leq N-2$,
 $\text{sem}(1) = n_2$, $\text{sem}(2) = 0$
 moves from P1 to P2 lead to S3, if $n_2 = N-1$
- S3 $n_1 = 1$, $n_2 = N-1$, $\text{sem}(1) = N-1$, $\text{sem}(2) = 0$
 moves from P1 to P3 lead to S4
- S4 $n_2 = N-1$, $n_3 = 1$, $\text{sem}(1) = N$, $\text{sem}(2) = 0$
 moves from P3 to P4 lead to S5
- S5 $n_2 = N-1$, $n_4 = 1$, $\text{sem}(1) = \text{sem}(2) = 0$
 moves from P2 to P4 lead to S6
- S6 $n_2 + n_4 = N$, $n_4 > 1$, $\text{sem}(1) = \text{sem}(2) = 0$
 moves from P4 to P5 lead to S7
- S7 $n_2 + n_4 + n_5 = N$, $1 \leq n_5 \leq N-2$,
 $\text{sem}(1) = 0$, $\text{sem}(2) = n_5$
 moves from P4 to P5 lead to S8, if $n_5 = N-5$
- S8 $n_2 + n_4 = 1$, $n_5 = N-1$, $\text{sem}(1) = 0$, $\text{sem}(2) = N-1$
 moves from P4 to P6 lead to S4'
- S4' $n_5 = N-1$, $n_6 = 1$, $\text{sem}(1) = 0$, $\text{sem}(2) = N$
 moves from P6 to P1 lead to S5'
- .
- .
- .

Table 4.1

The rest of the tree is omitted in table 4.1. It consists of sets S5', S6', S7', S8', that are connected and their descriptions are the same as those of S5, S6, S7, S8, respectively, where symbols $P(1+i)$, n_{1+i} are interchanged with symbols $P(1+j)$, n_{1+j} , respectively, for $i=0,1,2$ and $j=(i+3)\text{mod}6$, and $\text{sem}(1)$ is interchanged with symbol $\text{sem}(2)$. Note that the description of the set S4' can be obtained from that of S4 in the same manner.

INCLUSIONS

$$S1 \subset S6'; S2 \subset S7'; S3 \subset S8'; S5 \subset S6; S5' \subset S6'$$

REACHABILITY SET DESCRIPTION

S4 $n_2 = N-1, n_3 = 1, \text{sem}(1) = N, \text{sem}(2) = 0$
moves from P2 to P2 lead to *
moves from P3 to P4 lead to S6

S6 $n_2 + n_4 = N, n_4 > 1, \text{sem}(1) = \text{sem}(2) = 0$
moves from P2 to P4 lead to *
moves from P4 to P5 lead to S7

S7 $n_2 + n_4 + n_5 = N, 1 < n_5 < N-2,$
 $\text{sem}(1) = 0, \text{sem}(2) = n_5$
moves from P2 to P4 lead to *
moves from P4 to P5 lead to *, if $n_5 < N-2$
or lead to S8, if $n_5 = N-1$
moves from P5 to P5 lead to *

S8 $n_2 + n_4 = 1, n_5 = N-1, \text{sem}(1) = 0, \text{sem}(2) = N-1$
moves from P2 to P4 lead to *
moves from P4 to P6 lead to S4'
moves from P5 to P5 lead to *

S4' $n_5 = N-1, n_6 = 1, \text{sem}(2) = N, \text{sem}(1) = 0$
moves from P5 to P5 lead to *
moves from P6 to P1 lead to S6'

S6' $n_5 + n_1 = N, n_1 > 1, \text{sem}(2) = \text{sem}(1) = 0$
moves from P5 to P1 lead to *
moves from P1 to P2 lead to S7'

S7' $n_5 + n_1 + n_2 = N, 1 < n_2 < N-2,$
 $\text{sem}(2) = 0, \text{sem}(1) = n_2$
moves from P5 to P1 lead to *
moves from P1 to P2 lead to *, if $n_2 < N-2$
or lead to S8', if $n_2 = N-1$
moves from P2 to P2 lead to *

S8' $n_5 + n_1 = 1, n_2 = N-1, \text{sem}(2) = 0, \text{sem}(1) = N-1$
moves from P5 to P1 lead to *
moves from P1 to P3 lead to S4
moves from P2 to P2 lead to *

Table 4.2

Since (A1) is equivalent to:

$$- n_1 \times n_4 \leq 1 \text{ for all states}$$

it follows immediately from the description.

(A2) can be expressed in the form:

- there are no cycles satisfying the FDP such that $n_1 + n_2 + n_3 > 1$ along all states on the cycle;
and there are no cycles satisfying the FDP such that $n_4 + n_5 + n_6 > 1$ along all states on the cycle.

We will prove only the first part of the assertion as the second part will then be true by symmetry.

We apply the procedure FIND SCC of section 3 to obtain all SCCs of Δ , all states of which satisfy the predicate $p(s) = \{n_1 + n_2 + n_3 > 1\}$.

Step 1 gives the graph $\Gamma_{\bullet p}$ as in table 4.3.

S4•p $n_2 = N-1, n_3 = 1, \text{sem}(1) = N, \text{sem}(2) = 0$
moves from P2 to P2 lead to *
moves from P3 to P4 lead to S6•p

S6•p $n_2 + n_4 = N, n_4 > 1, n_2 > 1, \text{sem}(1) = \text{sem}(2) = 0$
moves from P2 to P4 lead to *
moves from P4 to P5 lead to S7•p

S7•p $n_2 + n_4 + n_5 = N, 1 < n_5 < N-2, n_2 > 1,$
 $\text{sem}(1) = 0, \text{sem}(2) = n_5$
moves from P2 to P4 lead to *
moves from P4 to P5 lead to *, if $n_5 < N-2$
or lead to S8•p, if $n_5 = N-1$
moves from P5 to P5 lead to *

S8•p $n_2 + n_4 = 1, n_5 = N-1, n_2 > 1, \text{sem}(1) = 0, \text{sem}(2) = N-1$
moves from P2 to P4 lead to *
moves from P5 to P5 lead to *

S6'•p $n_5 + n_1 = N, n_1 > 1, \text{sem}(2) = \text{sem}(1) = 0$
moves from P5 to P1 lead to *
moves from P1 to P2 lead to S7'•p

S7'•p $n_5 + n_1 + n_2 = N, 1 < n_2 < N-2,$
 $\text{sem}(2) = 0, \text{sem}(1) = n_2$
moves from P5 to P1 lead to *
moves from P1 to P2 lead to *, if $n_2 < N-2$
or lead to S8'•p, if $n_2 = N-1$
moves from P2 to P2 lead to *

S8'•p $n_5 + n_1 = 1, n_2 = N-1, n_1 + n_2 > 1,$
 $\text{sem}(2) = 0, \text{sem}(1) = N-1$
moves from P5 to P1 lead to *
moves from P1 to P3 lead to S4•p
moves from P2 to P2 lead to *

Table 4.3

Step 2 gives the following 7 SCCs in Γ •p:

1-st SCC in Γ •p:

S4•p $n_2 = N-1, n_3 = 1, \text{sem}(1) = N, \text{sem}(2) = 0$
moves from P2 to P2 lead to *

2-nd SCC in Γ •p:

S6•p $n_2 + n_4 = N, n_4 > 1, n_2 > 1, \text{sem}(1) = \text{sem}(2) = 0$
moves from P2 to P4 lead to *

3-rd SCC in Γ •p:

S7•p $n_2 + n_4 + n_5 = N$, $n_2 > 1$, $1 < n_5 < N-2$,
 $\text{sem}(1) = 0$, $\text{sem}(2) = n_5$
 moves from P2 to P4 lead to *
 moves from P4 to P5 lead to *, if $n_5 < N-2$
 moves from P5 to P5 lead to *

4-th SCC in $\Gamma \bullet p$:

S8•p $n_2 + n_4 = 1$, $n_5 = N-1$, $n_2 > 1$, $\text{sem}(1) = 0$, $\text{sem}(2) = N-1$
 moves from P2 to P4 lead to *
 moves from P5 to P5 lead to *

5-th SCC in $\Gamma \bullet p$:

S6'•p $n_5 + n_1 = N$, $n_1 > 1$, $\text{sem}(2) = \text{sem}(1) = 0$
 moves from P5 to P1 lead to *

6-th SCC in $\Gamma \bullet p$:

S7'•p $n_5 + n_1 + n_2 = N$, $1 < n_2 < N-2$,
 $\text{sem}(2) = 0$, $\text{sem}(1) = n_2$
 moves from P5 to P1 lead to *
 moves from P1 to P2 lead to *, if $n_2 < N-2$
 moves from P2 to P2 lead to *

7-th SCC in $\Gamma \bullet p$:

S8'•p $n_5 + n_1 = 1$, $n_2 = N-1$, $n_1 + n_2 > 1$,
 $\text{sem}(2) = 0$, $\text{sem}(1) = N-1$
 moves from P5 to P1 lead to *
 moves from P2 to P2 lead to *

Step 3 gives the following two loops as SCCs in graphs G_L for L equal to the 1-st, 3-rd, 4-th, 6-th, or 7-th SCC in $\Gamma \bullet p$: $P2 \rightarrow P2$ and $P5 \rightarrow P5$. These loops can carry the following 5 classes of SCCs in Δ :

S4•p $n_2 = N-1$, $n_3 = 1$, $n_2 > 1$, $\text{sem}(1) = N$, $\text{sem}(2) = 0$
 moves from P2 to P2 lead to *

S7•p $n_2 + n_4 + n_5 = N$, $1 < n_5 < N-2$, $n_2 > 1$,
 $\text{sem}(1) = 0$, $\text{sem}(2) = n_5$
 moves from P5 to P5 lead to *

S8•p $n_2 + n_4 = 1$, $n_5 = N-1$, $n_2 > 1$, $\text{sem}(1) = 0$, $\text{sem}(2) = N-1$
 moves from P5 to P5 lead to *

S7'•p $n_5 + n_1 + n_2 = N$, $1 < n_2 < N-2$,
 $\text{sem}(2) = 0$, $\text{sem}(1) = n_2$
 moves from P2 to P2 lead to *

S8' • $n_5 + n_1 = 1, n_2 = N-1, n_1 + n_2 > 1,$
 $\text{sem}(2) = 0, \text{sem}(1) = N-1$
 moves from P2 to P2 lead to *

But none of these SCCs satisfies the FDP, because for any SCC there is a position P_i such that n_i is a positive constant for all states of the SCC. (For example any SCC from S7 • satisfies condition $n_2 \equiv \text{const} > 1$). This proves (A2).

5. "Cessation of activity" synchronization.

The need in this synchronization, described in [5] arises in "producer-consumer" programs. When the supply of produced data is empty and there is no hope that any PE will produce more data, all PEs are to be trapped in a special section that registers "cessation of activity". As long as data can appear, no PEs should be trapped. The comprehensive representation of this example is rather complicated and requires us to represent not only the "cessation of activity" routine but also the maintenance of upper and lower bounds for buffer of stored data, and the "overflowed buffer" synchronization routine.⁷

We will not represent here all these programs because the analysis of them together is beyond the "manual" level and requires some automatization. Hoping that such automatization is possible, we represent here an idealized version of "cessation of activity" synchronization. The first step of idealization is to consider a buffer of unlimited size. Then the program would have the following form, where b is the upper bound for the number of pieces of

⁷The "overflowed buffer" state means: all PEs have produced data but no room is left in the buffer. Logically the "overflowed buffer" situation is the same as "cessation of activity". (Interchange "consuming" with "producing", the state "buffer empty" with the state "buffer full").

information in the buffer, w is the counter for the number of PEs sitting inside the control appendix. Initially $w = 0$. The initial value of b is immaterial providing $b > 0$.

COMMENT distributor

P1: work with data (produce or consume)
go to P2 (to insert a new piece of data)
or to P3 (to delete one previously stored piece of data)

COMMENT insertion section

P2: REPADD (b,1)
insert a piece of data into the buffer
go to P1

COMMENT deletion section

P3: if ($b \leq 0$) then go to P6

P4: if (REPADD (b,-1) ≤ -1) then go to P5
delete a piece of data from the buffer
go to P1

P5: REPADD (b,1)
go to P6

COMMENT control appendix

P6: REPADD (w,1)

P7: if ($b \leq 0$) then go to P9

COMMENT recover from control appendix

P8: REPADD (w,-1)
go to P3

P9: if ($w \leq N-1$) then go to P7

COMMENT registration of cessation of activity

P10: go to *

Unfortunately this program does not allow any compact REACHABILITY TREE: to exhaust all reachable sets one has at least to exhaust the buffer. (In section 7 we consider another example of the program that does not allow a compact REACHABILITY TREE). The next step of idealization is to eliminate counter b. Instead of b we introduce the binary flag e: $e = 1$ if the buffer is empty, $e = 0$ otherwise. Initially, $e = 0$. Now the program has the following form:

```
P1: go to P2 or P3
P2: e <- 0
    go to P1
P3: if (e = 1) then go to P6
P4: go to P1 or P5
P5: e <- 1
    go to P1
P6: REPADD (w,1)
P7: if (e = 1) then go to P9
P8: REPADD (w,-1)
    go to P3
P9: if (w < N-1) then go to P7
P10: go to *
```

Note that in the code, exterior positions (P1, P4 and P10) appear for the first time in our examples. We will not discuss here the correspondence between the latter program and the original one. (It can be proved that for each history of the latter program there is a corresponding history of the former. The opposite is not true). Note, that indivisibility of the operations $e <- 0$ and $e <- 1$ is provided by our interpretation of abstract programs (see section 2). If one wants to use this code as a concrete program one has to provide the indivisibility somehow.

We want to verify the following assertions about this program:

(A1) If there is no data to work ($e = 1$) for any time $t > t_1$, then there exists such a time t_2 that for all $t > t_2$ all PEs are registered as free from activity ($n_{10} = N$).

(A2) If there are PEs registered as free from activity ($n_{10} > 1$) at any time t_1 , then for any time $t > t_1$ there is no data to work ($e = 1$).

The REACHABILITY TREE, INCLUSIONS and RSD are represented in tables 5.1, 5.2.

REACHABILITY TREE

- S1 $n_1 = N$, $e = 0$, $w = 0$
moves from P1 to P2 lead to S2
- S2 $n_1 + n_2 = N$, $e = 0$, $w = 0$
moves from P1 to P3 lead to S3
- S3 $n_1 + n_2 + n_3 = N$, $e = 0$, $w = 0$
moves from P3 to P4 lead to S4
- S4 $n_1 + \dots + n_4 = N$, $e = 0$, $w = 0$
moves from P4 to P5 lead to S5
- S5 $n_1 + \dots + n_5 = N$, $e = 0$, $w = 0$
moves from P5 to P1 lead to S6
- S6 $n_1 + \dots + n_5 = N$, $n_1 > 1$, $e = 1$, $w = 0$
moves from P1 to P2 lead to S7
- S7 $n_1 + \dots + n_5 = N$, $n_1 + n_2 > 1$, $e = 1$, $w = 0$
moves from P1 to P3 lead to S8
- S8 $n_1 + \dots + n_5 = N$, $n_1 + n_2 + n_3 > 1$, $e = 1$, $w = 0$
moves from P3 to P6 lead to S9
- S9 $n_1 + \dots + n_6 = N$, $n_1 + n_2 + n_3 + n_6 > 1$, $e = 1$, $w = 0$
moves from P2 to P1 lead to S10
- S10 $n_1 + \dots + n_6 = N$, $n_1 > 1$, $e = 0$, $w = 0$
moves from P1 to P2 lead to S11
- S11 $n_1 + \dots + n_6 = N$, $n_1 + n_2 > 1$, $e = 0$, $w = 0$
moves from P1 to P3 lead to S12

S12 $n_1 + \dots + n_6 = N$, $n_1 + n_2 + n_3 > 1$, $e = 0$, $w = 0$
moves from P3 to P4 lead to S13

S13 $n_1 + \dots + n_6 = N$, $n_1 + \dots + n_4 > 1$, $e = 0$, $w = 0$
moves from P4 to P5 lead to S14

S14 $n_1 + \dots + n_6 = N$, $n_1 + \dots + n_5 > 1$, $e = 0$, $w = 0$
moves from P6 to P7 lead to S15

S15 $n_1 + \dots + n_7 = N$, $n_1 + \dots + n_5 > 1$, $e = 0$,
 $n_7 \leq N-1$, $w = n_7$
moves from P7 to P8 lead to S16

S16 $n_1 + \dots + n_8 = N$, $n_1 + \dots + n_5 > 1$, $e = 0$,
 $n_7 + n_8 \leq N-1$, $w = n_7 + n_8$
moves from P5 to P1 lead to S17

S17 $n_1 + \dots + n_8 = N$, $n_1 > 1$, $e = 1$,
 $n_7 + n_8 \leq N-1$, $w = n_7 + n_8$
moves from P1 to P2 lead to S18

S18 $n_1 + \dots + n_8 = N$, $n_1 + n_2 > 1$, $e = 1$,
 $n_7 + n_8 \leq N-1$, $w = n_7 + n_8$
moves from P1 to P3 lead to S19

S19 $n_1 + \dots + n_8 = N$, $n_1 + n_2 + n_3 > 1$, $e = 1$,
 $n_7 + n_8 \leq N-1$, $w = n_7 + n_8$
moves from P7 to P9 lead to S20

S20 $n_1 + \dots + n_9 = N$, $n_1 + n_2 + n_3 > 1$, $e = 1$,
 $n_7 + n_8 + n_9 \leq N-1$, $w = n_7 + n_8 + n_9$
moves from P3 to P6 lead to S21

S21 $n_1 + \dots + n_9 = N$, $n_1 + n_2 + n_3 + n_6 > 1$, $e = 1$,
 $n_7 + n_8 + n_9 \leq N-1$, $w = n_7 + n_8 + n_9$
moves from P2 to P1 lead to S22
moves from P6 to P7 lead to S27, if $n_7 + n_8 + n_9 \leq N-1$
or lead to S29, if $n_7 + n_8 + n_9 = N$

S22 $n_1 + \dots + n_9 = N$, $n_1 > 1$, $e = 0$, $w = n_7 + n_8 + n_9$
 $n_7 + n_8 + n_9 \leq N-1$
moves from P1 to P2 lead to S23

S23 $n_1 + \dots + n_9 = N$, $n_1 + n_2 > 1$, $e = 0$, $w = n_7 + n_8 + n_9$,
 $n_7 + n_8 + n_9 \leq N-1$
moves from P1 to P3 lead to S24

S24 $n_1 + \dots + n_9 = N$, $n_1 + n_2 + n_3 > 1$, $e = 0$,
 $n_7 + n_8 + n_9 \leq N-1$, $w = n_7 + n_8 + n_9$
moves from P3 to P4 lead to S25

S25 $n_1 + \dots + n_9 = N$, $n_1 + \dots + n_4 > 1$, $e = 0$,
 $n_7 + n_8 + n_9 \leq N-1$, $w = n_7 + n_8 + n_9$
moves from P4 to P5 lead to S26

- S26 $n_1 + \dots + n_9 = N$, $n_1 + \dots + n_5 \geq 1$, $e = 0$,
 $n_7 + n_8 + n_9 \leq N-1$, $w = n_7 + n_8 + n_9$
- S27 $n_1 + \dots + n_9 = N$, $e = 1$, $n_1 + n_2 + n_3 + n_6 + n_7 \geq 1$,
 $n_7 + n_8 + n_9 \leq N-1$, $w = n_7 + n_8 + n_9$
 moves from P7 to P9 lead to S28
- S28 $n_1 + \dots + n_9 = N$, $e = 1$, $n_1 + n_2 + n_3 + n_6 + n_7 + n_9 \geq 1$,
 $n_7 + n_8 + n_9 \leq N-1$, $w = n_7 + n_8 + n_9$
- S29 $n_7 + \dots + n_9 = N$, $e = 1$, $w = N$
 moves from P9 to P10 lead to S30
- S30 $n_7 + \dots + n_{10} = N$, $e = 1$, $w = N$
 moves from P8 to P3 lead to S31
- S31 $n_3 + n_7 + n_8 + n_9 + n_{10} = N$, $e = 1$, $n_3 \geq 1$,
 $n_7 + \dots + n_{10} \leq N-1$, $w = n_7 + \dots + n_{10}$
 moves from P3 to P6 lead to S32
- S32 $n_3 + n_6 + n_7 + n_8 + n_9 + n_{10} = N$, $e = 1$, $n_3 + n_6 \geq 1$,
 $n_7 + \dots + n_{10} \leq N-1$, $w = n_7 + \dots + n_{10}$

INCLUSIONS

$S1 \subset \dots \subset S5 \subset S26$;
 $S10 \subset \dots \subset S16 \subset S26$;
 $S6 \subset \dots \subset S9 \subset S28$;
 $S17 \subset \dots \subset S21 \subset S27 \subset S28$;
 $S29 \subset S30$;
 $S31 \subset S32$

Table 5.1

REACHABILITY SET DESCRIPTION

- S26 $n_1 + \dots + n_9 = N$, $n_1 + \dots + n_5 \geq 1$, $e = 0$,
 $n_7 + n_8 + n_9 \leq N-1$, $w = n_7 + n_8 + n_9$
moves from P1 to P2 lead to *
moves from P1 to P3 lead to *
moves from P2 to P1 lead to *
moves from P3 to P4 lead to *
moves from P4 to P1 lead to *
moves from P4 to P5 lead to *
moves from P5 to P1 lead to S28
moves from P6 to P7 lead to *
moves from P7 to P8 lead to *
moves from P8 to P3 lead to *
moves from P9 to P7 lead to *
- S28 $n_1 + \dots + n_9 = N$, $e = 1$, $n_1 + n_2 + n_3 + n_6 + n_7 + n_9 \geq 1$,
 $n_7 + n_8 + n_9 \leq N-1$, $w = n_7 + n_8 + n_9$
moves from P1 to P2 lead to *
moves from P1 to P3 lead to *
moves from P2 to P1 lead to S26
moves from P3 to P6 lead to *
moves from P4 to P1 lead to *
moves from P4 to P5 lead to *
moves from P5 to P1 lead to *
moves from P6 to P7 lead to *, if $n_7 + n_8 + n_9 \leq N-1$
or lead to S30, if $n_7 + n_8 + n_9 = N$
moves from P7 to P9 lead to *
moves from P8 to P3 lead to *
moves from P9 to P7 lead to *
- S30 $n_7 + \dots + n_{10} = N$, $e = 1$, $w = N$
moves from P7 to P9 lead to *
moves from P8 to P3 lead to S32
moves from P9 to P10 lead to *
moves from P10 to P10 lead to *
- S32 $n_3 + n_6 + n_7 + n_8 + n_9 + n_{10} = N$, $e = 1$, $n_3 + n_6 \geq 1$,
 $n_7 + \dots + n_{10} \leq N-1$, $w = n_7 + \dots + n_{10}$
moves from P3 to P6 lead to *
moves from P6 to P7 lead to *, if $n_3 + n_6 \geq 1$
or lead to S30, if $n_3 = n_6 = 0$
moves from P7 to P9 lead to *
moves from P8 to P3 lead to *
moves from P9 to P10 lead to *
moves from P10 to P10 lead to *

Table 5.2

It is easy to see that if $n_{10} = N$ happens at moment t' then it is true for all $t \geq t'$. Hence (A1) can be expressed in the form:

- there is no cycle satisfying the FDP such that the conditions $e = 1$ and $n_{10} < N$ are held for all states on cycle.

(A2) can be expressed in the form:

- for any 2 states s_1 and s_2 if $n_{10} \geq 1$ in s_1 and $e = 0$ in s_2 then there is no way from s_1 to s_2 in Δ .

To verify (A1) we use the procedure FIND SCC for $p(s) = \{e = 1 \ \& \ n_{10} \leq N-1\}$. We do not represent here the graph $\Gamma \bullet p$ obtained after step 1 and go directly to step 2 which gives the following 2 SCCs L in $\Gamma \bullet p$.

First SCC in $\Gamma \bullet p$ ($L=L1$):

S28 $\bullet p$ $n_1 + \dots + n_9 = N$, $e = 1$, $n_1 + n_2 + n_3 + n_6 + n_7 + n_9 \geq 1$,
 $n_7 + n_8 + n_9 \leq N-1$, $n_{10} \leq N-1$, $w = n_7 + n_8 + n_9$
 moves from P1 to P3 lead to *
 moves from P3 to P6 lead to *
 moves from P4 to P1 lead to *
 moves from P4 to P5 lead to *
 moves from P5 to P1 lead to *
 moves from P6 to P7 lead to *, if $n_7 + n_8 + n_9 \leq N-1$
 moves from P7 to P9 lead to *

Second SCC in $\Gamma \bullet p$ ($L=L2$):

S30 $\bullet p$ $n_7 + \dots + n_{10} = N$, $n_{10} \leq N-1$, $e = 1$, $w = N$
 moves from P7 to P9 lead to *
 moves from P8 to P3 lead to S32 $\bullet p$
 moves from P9 to P10 lead to *
 moves from P10 to P10 lead to *

S32 $\bullet p$ $n_3 + n_6 + n_7 + n_8 + n_9 + n_{10} = N$, $e = 1$, $n_3 + n_6 \geq 1$,
 $n_7 + \dots + n_{10} \leq N-1$, $w = n_7 + \dots + n_{10}$
 moves from P3 to P6 lead to *
 moves from P6 to P7 lead to *, if $n_3 + n_6 \geq 1$
 or lead to S30 $\bullet p$, if $n_3 = n_6 = 0$
 moves from P7 to P9 lead to *
 moves from P8 to P3 lead to *
 moves from P9 to P10 lead to *
 moves from P10 to P10 lead to *

L1 gives the graph $P4 \rightarrow P1 \rightarrow P3 \rightarrow P6 \rightarrow P7 \rightarrow P9, P4 \rightarrow P5 \rightarrow P1$ in G_A , which has no SCC.

L2 gives the graph $P8 \rightarrow P3 \rightarrow P6 \rightarrow P7 \rightarrow P9 \rightarrow P10 \rightarrow P10$, which in turn on step 3 of the procedure gives the only loop M, of the form $P10 \rightarrow P10$. This loop can only carry the following two classes of SCCs in $\Delta \bullet p$:

S30 $\bullet p$ $n_7 + \dots + n_{10} = N, n_{10} \leq N-1, e = 1, w = N$
 moves from P10 to P10 lead to *

S32 $\bullet p$ $n_3 + n_6 + n_7 + n_8 + n_9 + n_{10} = N, e = 1, n_3 + n_6 \geq 1,$
 $n_7 + \dots + n_{10} \leq N-1, w = n_7 + \dots + n_{10}$
 moves from P10 to P10 lead to *

But none of these SCCs satisfies the FDP, because there is always a position which contains a positive number of "sleeping" PEs. This proves (A1).

(A2) can be seen from the RSD in the following way. The property $n_{10} \geq 1$ can be true only for some states in S30 and S32. But neither of these sets has a state with $e = 0$ and all transitions from a state in $S30 \cup S32$ yield a state in $S30 \cup S32$.

So the program satisfies (A2).

6. Readers and writers.

The simplest variant of the program from [5] is taken here. Initially the counter sem is equal to N.

```
P1:  {...}

COMMENT distributor

P2:  go to P3 (to read) or go to P8 (to write)

COMMENT reader

P3:  if(sem ≤ 0) then go to *
P4:  if( REPADD (sem,-1) > 0) then go to P6
P5:  REPADD (sem,1)
     go to P3

COMMENT critical section, protected by sem

P6:  {...}
P7:  REPADD (sem, 1)
     go to P1

COMMENT writer

P8:  if(sem ≤ N-1) then go to *
P9:  if( REPADD (sem, -N) > 0) then go to P11
P10: REPADD (sem,N)
     go to P8

COMMENT critical section, protected by sem

P11: {...}
P12: REPADD (sem, N)
     go to P1
```

We want to verify the following assertions about the program:

(A1) No more than 1 writer can write, i.e. stay in P11.

(A2) While the writer is writing no readers can read, i.e. stay in P6.

(A3) While any positive number of readers are reading no one writer can write.

(A4) For any time t such that no PEs are in the critical section at time t , there exists a time $t' > t$ such that some PE is in the critical section at time t' .

We can rewrite this program in the form of the following abstract program.

```
P1: go to P2 or to P6
P2: if(sem ≤ 0) then go to *
P3: if( REPADD (sem,-1) > 0) then go to P5
P4: REPADD (sem,1)
    go to P2
P5: REPADD (sem, 1)
    go to P1
P6: if(sem ≤ N-1) then go to *
P7: if( REPADD (sem, -N) > 0) then go to P9
P8: REPADD (sem,N)
    go to P6
P9: REPADD (sem, N)
    go to P1
```

The REACHABILITY TREE, INCLUSIONS and RSD are represented in tables 6.1, 6.2.

REACHABILITY TREE

- S1 $n_1 = N$, sem = N
moves from P1 to P2 lead to S2
- S2 $n_1 + n_2 = N$, sem = N
moves from P2 to P3 lead to S3
- S3 $n_1 + n_2 + n_3 = N$, sem = N
moves from P1 to P6 lead to S4
- S4 $n_1 + n_2 + n_3 + n_6 = N$, sem = N
moves from P6 to P7 lead to S5
- S5 $n_1 + n_2 + n_3 + n_6 + n_7 = N$, sem = N
moves from P3 to P5 lead to S6
moves from P7 to P9 lead to S11
- S6 $n_1 + n_2 + n_3 + n_5 + n_6 + n_7 = N$,
 $n_5 > 1$, sem = $N - n_5$
moves from P7 to P8 lead to S7
- S7 $n_1 + n_2 + n_3 + n_5 + n_6 + n_7 + n_8 = N$,
 $n_5 > 1$, $n_8 > 1$, sem = $N \times (1 - n_8) - n_5$
moves from P5 to P1 lead to S8
- S8 $n_1 + n_2 + n_3 + n_5 + n_6 + n_7 + n_8 = N$,
 $n_1 + n_5 > 1$, $n_8 > 1$, sem = $N \times (1 - n_8) - n_5$
moves from P1 to P2 lead to S9

S9 $n_1 + n_2 + n_3 + n_5 + n_6 + n_7 + n_8 = N$,
 $n_1 + n_2 + n_5 \geq 1$, $n_8 \geq 1$,
 $sem = N \times (1 - n_8) - n_5$
 moves from P1 to P6 lead to S10

S10 $n_1 + n_2 + n_3 + n_5 + n_6 + n_7 + n_8 = N$,
 $n_1 + n_2 + n_5 + n_6 \geq 1$, $n_8 \geq 1$,
 $sem = N \times (1 - n_8) - n_5$

S11 $n_1 + n_2 + n_3 + n_6 + n_7 + n_9 = N$,
 $n_9 = 1$, $sem = 0$
 moves from P3 to P4 lead to S12

S12 $n_1 + \dots + n_4 + n_6 + n_7 + n_9 = N$,
 $n_9 = 1$, $sem = -n_4$
 moves from P7 to P8 lead to S13

S13 $n_1 + \dots + n_4 + n_6 + \dots + n_9 = N$,
 $n_9 = 1$, $sem = -N \times n_8 - n_4$
 moves from P9 to P1 lead to S14, if $n_8 = 0$, and $n_4 \geq 1$
 or lead to S23, if $n_8 \geq 1$

S14 $n_1 + \dots + n_4 + n_6 + n_7 = N$
 $n_4 \geq 1$, $n_1 \geq 1$,
 $sem = N - n_4$
 moves from P1 to P2 lead to S15

S15 $n_1 + \dots + n_4 + n_6 + n_7 = N$
 $n_4 \geq 1$, $n_1 + n_2 \geq 1$,
 $sem = N - n_4$
 moves from P1 to P6 lead to S16

S16 $n_1 + \dots + n_4 + n_6 + n_7 = N$
 $n_4 \geq 1$, $n_1 + n_2 + n_6 \geq 1$,
 $sem = N - n_4$
 moves from P2 to P3 lead to S17

S17 $n_1 + \dots + n_4 + n_6 + n_7 = N$
 $n_4 \geq 1$, $n_1 + n_2 + n_3 + n_6 \geq 1$,
 $sem = N - n_4$
 moves from P3 to P5 lead to S18

- S18 $n_1 + \dots + n_7 = N$
 $n_4 \geq 1, n_1 + n_2 + n_3 + n_5 + n_6 \geq 1$
 $\text{sem} = N - n_4 - n_5$
 moves from P7 to P8 lead to S19
- S19 $n_1 + \dots + n_8 = N, n_8 \geq 1,$
 $n_4 \geq 1, n_1 + n_2 + n_3 + n_5 + n_6 \geq 1,$
 $\text{sem} = N \times (1 - n_8) - n_4 - n_5$
 moves from P3 to P4 lead to S20
 moves from P4 to P2 lead to S22
- S20 $n_1 + \dots + n_8 = N, n_8 \geq 1,$
 $n_4 \geq 2,$
 $\text{sem} = N \times (1 - n_8) - n_4 - n_5$
 moves from P4 to P2 lead to S21
- S21 $n_1 + \dots + n_8 = N, n_8 \geq 1,$
 $n_2 + n_4 \geq 2,$
 $\text{sem} = N \times (1 - n_8) - n_4 - n_5$
- S22 $n_1 + \dots + n_8 = N, n_8 \geq 1,$
 $n_2 \geq 1, n_1 + n_2 + n_3 + n_5 + n_6 \geq 2$
 $\text{sem} = N \times (1 - n_8) - n_4 - n_5$
- S23 $n_1 + \dots + n_4 + n_6 + n_7 + n_8 = N, n_8 \geq 1,$
 $n_1 \geq 1,$
 $\text{sem} = N \times (1 - n_8) - n_4$
 moves from P1 to P2 lead to S24
- S24 $n_1 + \dots + n_4 + n_6 + n_7 + n_8 = N, n_8 \geq 1,$
 $n_1 + n_2 \geq 1,$
 $\text{sem} = N \times (1 - n_8) - n_4$
 moves from P1 to P6 lead to S25
- S25 $n_1 + \dots + n_4 + n_6 + n_7 + n_8 = N, n_8 \geq 1,$
 $n_1 + n_2 + n_6 \geq 1,$
 $\text{sem} = N \times (1 - n_8) - n_4$

Table 6.1

S13 $n_1 + \dots + n_4 + n_6 + \dots + n_9 = N$,
 $n_9 = 1$, $\text{sem} = -N \times n_8 - n_4$
 moves from P1 to P2 lead to *
 moves from P1 to P6 lead to *
 moves from P2 to P2 lead to *
 moves from P3 to P4 lead to S19
 moves from P4 to P2 lead to *
 moves from P6 to P6 lead to *
 moves from P7 to P8 lead to *
 moves from P8 to P6 lead to *
 moves from P9 to P1 lead to S18, if $n_8 = 0$, and $n_4 > 1$
 or lead to S25, if $n_8 > 1$
 or lead to S5, if $n_8 = n_4 = 0$

S18 $n_1 + \dots + n_7 = N$
 $n_4 > 1$, $n_1 + n_2 + n_3 + n_5 + n_6 > 1$
 $\text{sem} = N - n_4 - n_5$
 moves from P1 to P2 lead to *
 moves from P1 to P6 lead to *
 moves from P2 to P3 lead to *
 moves from P3 to P5 lead to *
 moves from P4 to P2 lead to *, if $n_4 > 1$
 or lead to S6, if $n_4 = 0$, $n_5 > 1$
 or lead to S5, if $n_4 = n_5 = 0$
 moves from P5 to P1 lead to *
 moves from P6 to P6 lead to *

S19 $n_1 + \dots + n_8 = N$, $n_8 > 1$,
 $n_4 > 1$, $n_1 + n_2 + n_3 + n_5 + n_6 > 1$,
 $\text{sem} = N \times (1 - n_8) - n_4 - n_5$
 moves from P1 to P2 lead to *
 moves from P1 to P6 lead to *
 moves from P2 to P2 lead to *
 moves from P3 to P4 lead to S21
 moves from P4 to P2 lead to S22
 moves from P5 to P1 lead to *
 moves from P6 to P6 lead to *
 moves from P7 to P8 lead to *
 moves from P8 to P6 lead to *, if $n_8 > 1$
 or lead to S18, if $n_8 = 0$

- S21 $n_1 + \dots + n_8 = N$, $n_8 > 1$,
 $n_2 + n_4 > 2$,
 $\text{sem} = N \times (1 - n_8) - n_4 - n_5$
 moves from P1 to P2 lead to *
 moves from P1 to P6 lead to *
 moves from P2 to P2 lead to *
 moves from P3 to P4 lead to *
 moves from P4 to P2 lead to *
 moves from P5 to P1 lead to *
 moves from P6 to P6 lead to *
 moves from P7 to P8 lead to *
 moves from P8 to P6 lead to *, if $n_8 > 1$
 or lead to S18, if $n_8 = 0$, $n_4 > 1$
 or lead to S6, if $n_8 = n_4 = 0$, $n_5 > 1$
 or lead to S5, if $n_4 = n_5 = n_8 = 0$
- S22 $n_1 + \dots + n_8 = N$, $n_8 > 1$,
 $n_2 > 1$, $n_1 + n_2 + n_3 + n_5 + n_6 > 2$
 $\text{sem} = N \times (1 - n_8) - n_4 - n_5$
 moves from P1 to P2 lead to *
 moves from P1 to P6 lead to *
 moves from P2 to P2 lead to *
 moves from P3 to P4 lead to S21
 moves from P4 to P2 lead to *
 moves from P5 to P1 lead to *
 moves from P6 to P6 lead to *
 moves from P7 to P8 lead to *
 moves from P8 to P6 lead to *, if $n_8 > 1$
 or lead to S18, if $n_8 = 0$, $n_4 > 1$
 or lead to S6, if $n_8 = n_4 = 0$, $n_5 > 1$
 or lead to S5, if $n_4 = n_5 = n_8 = 0$
- S25 $n_1 + \dots + n_4 + n_6 + n_7 + n_8 = N$, $n_8 > 1$,
 $n_1 + n_2 + n_6 > 1$,
 $\text{sem} = N \times (1 - n_8) - n_4$
 moves from P1 to P2 lead to *
 moves from P1 to P6 lead to *
 moves from P2 to P2 lead to *
 moves from P3 to P4 lead to *
 moves from P4 to P2 lead to *
 moves from P5 to P1 lead to *
 moves from P6 to P6 lead to *
 moves from P7 to P8 lead to *
 moves from P8 to P6 lead to *, if $n_8 > 1$
 or lead to S18, if $n_8 = 0$, $n_4 > 1$
 or lead to S5, if $n_4 = n_8 = 0$

Table 6.2

Since properties (A1), (A2), (A3) together can be expressed as

$$- n_9 \leq 1, n_5 \times n_9 = 0 \text{ for all states,}$$

they follow immediately from the description.

(A4) can be expressed in the form:

- there are no cycles satisfying the FDP such that $n_5 = n_9 = 0$ along all the states on the cycle.

We apply the procedure FIND SCC for $p(s) = \{n_5 = n_9 = 0\}$ and find out that there are only 7 SCCs L in $\Gamma \bullet p$. These correspond to the single nodes $S5 \bullet p$, $S10 \bullet p$, $S18 \bullet p$, $S19 \bullet p$, $S21 \bullet p$, $S22 \bullet p$, $S25 \bullet p$, looping to themselves. It is easy to verify that only the following two loops can carry moves in the SCC under question. These moves are

moves from $P2$ to $P2$ lead to *

moves from $P6$ to $P6$ lead to *

Now (A4) follows from the fact that none of the sets $S10 \bullet p$, $S18 \bullet p$, $S19 \bullet p$, $S21 \bullet p$, $S22 \bullet p$, $S25 \bullet p$ has a state, satisfying condition $n_2 + n_6 = N$ that would have been the only possibility to arrange the cycle, satisfying the FDP.

7. Conclusion.

To build a compact RSD we reduce a REACHABILITY TREE that in turn must be compact. The first "producer-consumer" program presented in section 5 (which we henceforth refer to as PC) does not allow a compact REACHABILITY TREE for the obvious reason that it has an unbounded

counter: For any fixed number of PEs, N , any REACHABILITY TREE for PC is infinite. In this section we present a less trivial example that can not possess any compact REACHABILITY TREE independent of N . However unlike the PC for any given N the REACHABILITY TREE is finite. This example possesses the RSD consisting of 2 sets as given in table 7.1. This program consists of the following code with initially $\text{sem} = N-1$.

```

P1:  if (REPADD (sem,-1) > 0) then go to P3

P2:  REPADD (sem,1)
      go to P1

P3:  REPADD (sem,1)
      go to P1

```

Note that this code is equivalent to the incorrect PV-semaphore program of section 1; the only difference between these two programs is the initial value of sem . If the initial value of sem is independent of N , then the program possesses a compact REACHABILITY TREE.

REACHABILITY SET DESCRIPTION

```

S1   $n_1 + n_2 + n_3 = N$ ,  $n_1 \geq 2$ ,  $\text{sem} = n_1 - 1$ 
      moves from P1 to P3 lead to *, if  $n_1 \geq 2$ 
      or lead to S2, if  $n_1 = 1$ 
      moves from P2 to P1 lead to *
      moves from P3 to P1 lead to *

S2   $n_1 + n_2 + n_3 = N$ ,  $n_1 \leq 1$ ,  $n_1 + n_2 \geq 1$ ,  $\text{sem} = n_1 - 1$ 
      moves from P1 to P2 lead to *
      moves from P2 to P1 lead to *, if  $n_1 \leq 1$ 
      or lead to S1, if  $n_1 \geq 2$ 
      moves from P3 to P1 lead to *, if  $n_1 \leq 1$ 
      or lead to S1, if  $n_1 \geq 2$ 

```

Table 7.1

Strictly speaking we can not prove that the program can not have compact REACHABILITY TREE because we have not defined a REACHABILITY TREE. (Such a definition exceeds the range of the paper). A brief outline of the proof follows:

Imagine a parallel computer executing our abstract programs, which consist of (I) and (E) statements as defined in section 2. We suppose that each operation (including simultaneous Replace-f operations) is effected in a single cycle.

Let us call a program compact with respect to the given initial state s_0 , if there is a time T_0 independent on N such that any state in $R(s_0)$ can be reached from s_0 within time T_0 .

It can be shown that if a program has a compact REACHABILITY TREE then it is compact. It can also be shown that the program given above is not compact because the state $\{n_1 = 0, n_2 = N, n_3 = 0; \text{sem} = -1\}$ can not be reached from the initial state $\{n_1 = N, n_2 = n_3 = 0; \text{sem} = N-1\}$ in time asymptotically less than $\Omega(N)$.

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